#### **ORIGINAL ARTICLE**



# Safe implementation of hand held steerable laparoscopic instruments: a survey among EAES surgeons

S. F. Hardon<sup>1,2</sup> • A. M. Rahimi<sup>1</sup> · R. R. Postema<sup>1,2</sup> · E. Willuth<sup>3</sup> · Y. Mintz<sup>4,6</sup> · A. Arezzo<sup>5,6</sup> · J. Dankelman<sup>2</sup> · F. Nickel<sup>3,6</sup> · T. Horeman<sup>2,6</sup> on behalf of the EAES Technology Committee Study Group

Received: 9 December 2021 / Accepted: 14 February 2022 © The Author(s) 2022

#### **Abstract**

The complexity of handheld steerable laparoscopic instruments (SLI) may impair the learning curve compared to conventional instruments when first utilized. This study aimed to provide the current state of interest in the use of SLI, the current use of these in daily practice and the type of training which is conducted before using SLI in the operating room (OR) on real patients. An online survey was distributed by European Association of Endoscopic Surgery (EAES) Executive Office to all active members, between January 4th and February 3rd, 2020. The survey consisted of 14 questions regarding the usage and training of steerable laparoscopic instruments. A total of 83 members responded, coming from 33 different countries. Twenty three percent of the respondents using SLI, were using the instruments routinely and of these 21% had not received any formal training in advance of using the instruments in real patients. Of all responding EAES members, 41% considered the instruments to potentially compromise patient safety due to their complexity, learning curve and the inexperience of the surgeons. The respondents reported the three most important aspects of a possible steerable laparoscopic instruments training curriculum to be: hands-on training, safe tissue handling and suturing practice. Finally, a major part of the respondents consider force/pressure feedback data to be of significant importance for implementation of training and assessment of safe laparoscopic and robotic surgery. Training and assessment of skills regarding safe implementation of steerable laparoscopic instruments is lacking. The respondents stressed the need for specific hands-on training during which feedback and assessment of skills should be guaranteed before operating on real patients.

Keywords Laparoscopy · Robot-assisted surgery · Steerable instruments · Patient safety · Survey

S. F. Hardon s.hardon@amsterdamumc.nl

Published online: 13 April 2022

- Department of Surgery, Amsterdam UMC-VU University Medical Center, Room ZH 7F005, De Boelelaan 1117, 1081HV Amsterdam, The Netherlands
- Department of BioMechanical Engineering, Delft University of Technology, Delft, The Netherlands
- Department of General, Visceral and Transplantation Surgery, Heidelberg University Hospital, Heidelberg, Germany
- Department of General Surgery, Hadassah-Hebrew University Medical Center, Jerusalem, Israel
- Department of Surgical Sciences, Università degli Studi di Torino, Turin, Italy
- Technology Committee, European Association of Endoscopic Surgery (EAES), Veldhoven, The Netherlands

#### Introduction

Since the late 1980s, robot-assisted surgery (RAS) has been gaining ground and has become the standard of care for several complex surgical procedures [1–7]. One of the advantages of RAS is the use of (distally) articulating robotic instruments which increase the degrees of freedom. However, due to the high acquisition and operating costs of RAS, the desire for a more affordable alternative has increased [8–10]. These more affordable alternatives should benefit both the patient and the surgeon [11, 12]. Consequently, hand held steerable laparoscopic instruments (SLI) were developed, offering part of the benefits that the robotic instruments have, but with reduction of the overall costs [10, 13, 14]. In recent years, the usage of SLI increased predominantly as a result of the interest in single-incision laparoscopy and the improved ergonomics for the surgeon's



## Table 1 Survey questions

- Q1. Are you interested in using steerable (handheld) instruments during your procedure? (yes/no/other)
- Q2. How often did you try a new steerable laparoscopic instrument in the operating room (OR)? (0-5 times, 5-10 times, 10-20 times, > 20 times)
- Q3. What was the name/brand of the instrument? By which company was it manufactured?
- Q4. Did you receive any specific training in advance of using a steerable instrument in the OR? (yes/no)
- Q5. If so, what type of training did you receive before using the instrument in the OR?
- (Demonstration by instructor, theoretical (eLearning, instruction form, booklet), hands-on box training, VR training, Cadaver training, proctoring in the OR, other than the above mentioned, I did not receive any specific training)
- Q6. Based on your expert opinion, do you see any potential risks in using steerable instruments in complex laparoscopic procedures? (yes/no/other)
- Q7. Please provide three aspects of training we should mainly focus on, in case of training with new steerable instruments:
- Q8. Do you think it is important to use force/pressure data as measures for safe laparoscopic surgery during assessment in and outside the OR? (Please specify: yes/no)
- Q9. Do you think it would be good or necessary to have tissue force/pressure data integrated during robot-assisted surgery (e.g., da Vinci) for training and/or for clinical routine? (Please specify: yes/no)
- Q10. Do you actually use steerable instruments routinely? If so, during what kind of procedures it is most beneficial to use these compared to conventional laparoscopic instruments? (Please specify: yes/no)
- Q11. What is your profession?
- Q12. What is your nationality?
- Q13. What is your gender?
- Q14. If a course or training for safe use of steerable instruments was organized by the EAES during the 2020 congress in Poland, would you be interested in attending it? (yes/no/other)

hand compared to conventional laparoscopic instruments [15–18].

The benefits and drawbacks of steerable instruments have been extensively reported in previous studies [15, 18–20]. Steerable instruments improve the range of motion and increase the degrees of freedom. Furthermore, by increasing the degree of freedom the physical strain and musculoskeletal pain of the surgeon's upper extremities decreased. [15, 21, 22]. Training courses with box trainers and virtual reality trainers using conventional laparoscopic instruments improve surgical skills [23–26]. However, the complexity of the SLI may result in a more shallow learning curve and, therefore, may require additional training to pursue mastery of skills. The angular amplification of the instrument tip and the more complex handle controls due to the increased degrees of freedom could overwhelm the surgeon and cause an initial longer training process [21, 27].

The aim of this study consisted of surveying members of the European Association of Endoscopic Surgery (EAES) to analyze and provide the current state of interest in the usage of steerable instruments. Moreover, we determined the current perceptions and use of the steerable instruments in daily practice and the type of training which has been conducted prior to using the instruments during laparoscopic surgery.

#### Methods

An online survey was conducted using a questionnaire designed and distributed by the European Association of Endoscopic Surgery (EAES) Executive Office to all active members of the EAES. The survey was conducted between January 4th and February 3rd, 2020. The survey consisted of 14 questions, presented in Table 1, regarding the usage and training of steerable laparoscopic instruments. Furthermore, the questions were designed to determine the opinion regarding objective assessment of the surgical performance with steerable instruments. GraphPad (Prism 9.0.0, San Diego, California USA) was used for frequency distribution and to generate the graphs. This anonymous survey was exempt from IRB approval.

## Results

A total of 83 (out of 3582) active members, of whom 80 were practicing surgeons, responded. The respondents originated from 33 countries, with the highest proportion from the Netherlands (14%), Italy (11%) and the United Kingdom (6%). The respondents held a position either as a surgeon (94%), a fellow (1%), or a resident (5%).

The vast majority of 75 participants (90%) was interested in using SLI during surgery in the OR (Fig. 1). Of the respondents, 61 (74%) had previously utilized a new SLI in the OR, but less than 5 times, 9 (11%) responded 5–10 times,



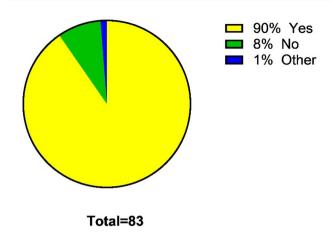


Fig. 1 Percentage of respondents interested in steerable instruments

and 12 (15%) confirmed they had used SLI more than 20 times in the OR (Fig. 2).

Of all surgeons who used SLI in the OR, 23% used it routinely, and most commonly to perform colorectal surgery procedures. When asked about the brand and company of the previously used SLI, the members responded with 23 different brands and companies, of which 17% Karl Storz SE & Co. KG (Tuttlingen, Germany), 17% Medtronic plc (Dublin, Ireland), 14% Alphatron Surgical B.V. (Rotterdam, The Netherlands) and 10% Tuebingen Scientific Medical GmbH (Tuebingen, Germany) were the most common (Fig. 3).

Twenty three percent of the respondents using SLI, were using SLI routinely and of this group twenty one percent had not received any specific training in advance of using the SLI in the OR (Fig. 4). If the participant had received training, the three most common types of training consisted

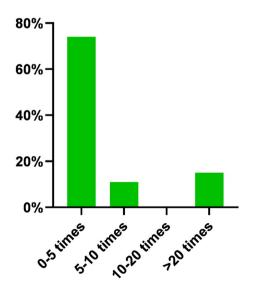


Fig. 2 Amount of times the steerable laparoscopic instruments were used on patients by the respondents using SLI

of: demonstration by instructor (34%), hands-on box training (31%) and theoretical training (eLearning, instruction form or booklet) (17%) (Fig. 5). Regarding potential risks of SLI concerning patient safety, 46% of the respondents foresaw no risk. Yet, 41% of respondents considered patient safety to be compromised with the introduction of SLI. The most frequent argument given for no risk was that before using SLI training is essential and only a good trained surgeon should perform surgery with steerable instruments and thus reducing the risk. The most common mentioned reason for potential risks consisted of the difficult and shallow learning curve and the lack of experience of the surgeons.

The three most reported aspects of training for steerable laparoscopic instruments were tissue handling, hands-on training and suturing practice. Fifty respondents (60%) reported that force/pressure data, with regard to tissue handling skills, is of significant importance for the assessment of safe laparoscopic surgery in and outside of the OR. In addition, 56 out of 83 respondents (67%) answered that it is necessary to have force/pressure data integrated during robotic surgery for training and/or clinical routine.

Below listed the most frequently mentioned manufacturers and instruments (Fig. 3), a short example that was provided by the respondents and the number (%) of users.

- 1. Karl Storz SE & Co. KG (Tuttlingen, Germany) (Fig. 3A), Articulating Needle Holder (17%).
- 2. Medtronic plc (Dublin, Ireland) (Fig. 3B), Covidien SILS<sup>TM</sup> Stitch articulating suturing device (17%).
- 3. Alphatron Surgical B.V. (Rotterdam, The Netherlands) (Fig. 3C), FlexDex system (14%).
- 4. Tuebingen Scientific Medical GmbH (Tuebingen, Germany) (Fig. 3D), Radius surgical system (10%).
- 5. B. Braun (Melsungen, Germany) (Fig. 3E), Caiman® 5 Articulating Maryland (3%).
- 6. Deam Products B.V. (Roden, The Netherlands) (Fig. 3F), LaproFlex (3%).
- 7. Johnson & Johnson (New Brunswick, New Jersey, United States) (Fig. 3G), ENSEAL G2 Articulating Tissue Sealer (3%).

### **Discussion**

This study, conducted with an questionnaire among EAES members, provided insight and perceptions regarding the implementation and adoption of SLI. Moreover, the results indicate to what extent specific skills for SLI have been trained and assessed before operating on real patients. The vast majority of the respondents had interest in using steerable instruments. However, only a small fraction was using the steerable laparoscopic instruments routinely. Furthermore, twenty one percent of this group did not receive



Fig. 3 Most commonly reported

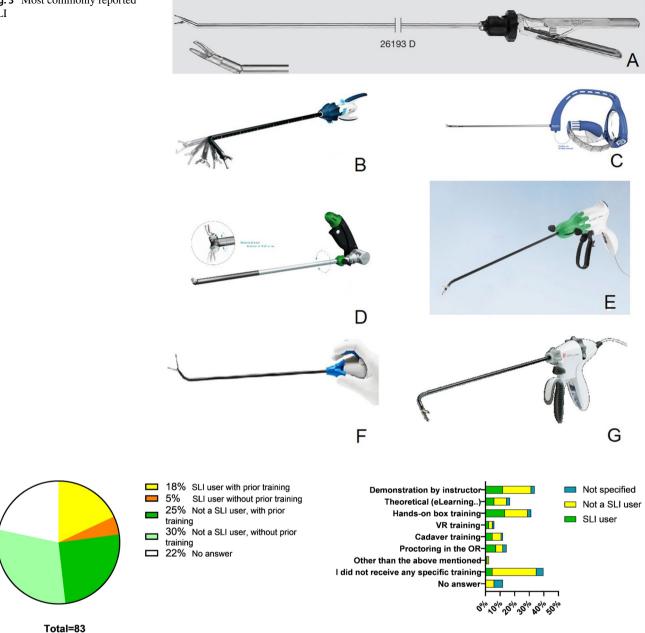


Fig. 4 Percentage of members which had received prior training

any form of prior training regarding steerable laparoscopic instruments. The respondents that did receive training, replied that the training consisted mainly of demonstration by an instructor or hands-on box training.

The majority of responding EAES members raised concerns on risks for patient safety, due to a shallow learning curve and the inexperience of the surgeon, when introducing the use of SLI. With this in mind the respondents determined the three most important aspects of steerable laparoscopic instruments to be: safe tissue handling, hands-on training and suturing practice. Furthermore, there was consensus

Fig. 5 Types of received training before using the instrument without supervision in the OR on patients. Combination of options are possible

among the respondents on the use of force-based feedback on tissue handling skills and its importance for the assessment of safe laparoscopic surgery. This same consensus, regarding the force/pressure data, consists for robotic surgery training.

Previous studies have compared conventional and steerable laparoscopic instruments in performance, ergonomics, learning curve and (the lack of) training [15, 18, 27, 28]. Santos et al. [28] compared two groups of medical students (n=45) with one group receiving laparoscopic training



with conventional instruments, and the other group receiving single-incision laparoscopy training with articulating instruments. The groups performed laparoscopic and single incision laparoscopic peg transfer and pattern cutting tasks. The learning curve for the articulating instruments was longer compared to conventional instruments and the performance with conventional instruments was superior. Besides, Uysal et al. (2020) [27] performed a randomized cross-over study with fifty laparoscopic novices comparing conventional and articulating laparoscopic instruments in completing the European training in basic laparoscopic urological skills (E-BLUS). The conventional laparoscopic instruments group had a better performance, with the longer learning curve of the articulating instruments being one of the possible reasons for this outcome. Corker et al. [18] compared articulating versus conventional instruments and also the combination of both instruments. This study consisted of three groups of surgeons with different combinations of instruments (n = 21): two articulating instruments, two conventional, and a combination of both. The groups performed a peg transfer task and a pattern-cutting task. The group with one articulating and one conventional laparoscopic instrument performed best in the peg transfer task. Finally, Sánchez-Margallo et al. [15] performed a study comparing six laparoscopic surgeons while using both conventional and a handheld motor-driven laparoscopic needle holder during three different suturing tasks. In this study, no significant differences were observed between the instruments regarding performance. However, the SLI did result in better outcomes with regards to ergonomics.

A limitation of this study is possible participation bias. EAES members who are more interested in SLI are more likely to participate in the survey, this also follows from the responses as ninety percent of the respondents was interested in SLI. Furthermore, a relatively small number of EAES members participated in the survey. A strength of this survey is the diversity in the country of origin of the respondents providing a variety in experience. Moreover, the respondents had experience with a large variety of SLI brands and, therefore, contributing to the survey with a more diverse experience.

Mainly driven by the large interest in SLI combined with an indicated uncertainty in the ability to safely control the instruments during complex surgical tasks as tissue manipulation or suturing, it is advisable to develop training initiatives for technical skills training and assessment specific for SLI. This training should allow residents and surgeons to practice with any type of SLI in a realistic setting using for example a physical hands-on trainer to overcome the learning curve for these instruments. Based on our previous results [26, 29, 30] and based on the outcomes of this

present study, the training system ideally provides objective performance feedback that reflect safe tissue handling. Doing so, surgeons can train new specific technical skills to control SLI. Adequate assessment of tissue interaction forces and unintentional errors at the end of training may reduce exerted forces and minimize tissue trauma when first utilizing SLI in real patients. [26, 30, 31]

#### **Conclusion**

Training and assessment of technical skills for safe use of steerable laparoscopic instruments is lacking. Despite the large interest in these instrument, there are limited training initiatives and few surgeons have been trained sufficiently. According to the responding EAES members in this study, hands-on box trainers must be used for training of specific technical skills. Moreover, the respondents stressed the importance of objective force-based feedback to train safe handling of tissues before operating on real patients.

**Acknowledgements** The authors sincerely thank all responding surgeons for their contribution.

Funding Not applicable.

#### **Declarations**

Conflict of interest Drs. Sem Hardon, Masie Rahimi, Roelf Postema, Estelle Willuth, Yoav Mintz, Alberto Arezzo and Prof. Jenny Dankelman have no conflict of interest or financial ties to disclose. Dr. Felix Nickel reports receiving travel support for conference participation as well as equipment provided for laparoscopic surgery courses by Karl Storz, Johnson & Johnson, Intuitive Surgical, Cambridge Medical Robotics, and Medtronic. Dr. ir. Tim Horeman is founder and shareholder of the TU-Delft MedTech startup Medishield Delft BV.

Ethical approval Not applicable.

Research involving human participants and/or animals Not applicable.

Informed consent Not applicable.

**Open Access** This article is licensed under a Creative Commons Attribution 4.0 International License, which permits use, sharing, adaptation, distribution and reproduction in any medium or format, as long as you give appropriate credit to the original author(s) and the source, provide a link to the Creative Commons licence, and indicate if changes were made. The images or other third party material in this article are included in the article's Creative Commons licence, unless indicated otherwise in a credit line to the material. If material is not included in the article's Creative Commons licence and your intended use is not permitted by statutory regulation or exceeds the permitted use, you will need to obtain permission directly from the copyright holder. To view a copy of this licence, visit http://creativecommons.org/licenses/by/4.0/.



## References

- Lane T (2018) A short history of robotic surgery. Ann R Coll Surg Engl 100:5–7. https://doi.org/10.1308/rcsann.supp1.5
- George EI, Brand TC, LaPorta A, Marescaux J, Satava RM (2018)
  Origins of robotic surgery: from skepticism to standard of care.
  JSLS J Soc Laparoendosc Surg. https://doi.org/10.4293/JSLS.
  2018.00039
- Chopra S, Srivastava A, Tewari A (2012) Robotic radical prostatectomy: the new gold standard, Arab. J Urol 10:23–31. https://doi.org/10.1016/j.aju.2011.12.005
- Stafford AT, Walsh RM (2015) Robotic surgery of the pancreas: the current state of the art. J Surg Oncol 112:289–294. https://doi. org/10.1002/jso.23952
- Shay SG, Chrin JD, Wang MB, Mendelsohn AH (2019) Initial and long-term retention of robotic technical skills in an otolaryngology residency program. Laryngoscope 129:1380–1385. https:// doi.org/10.1002/lary.27425
- Health Quality Ontario (2010) Robotic-assisted minimally invasive surgery for gynecologic and urologic oncology: an evidence-based analysis. Ont Health Technol Assess Ser 10: 1–118. http://www.ncbi.nlm.nih.gov/pubmed/23074405 (Accessed January 31, 2021).
- Willuth E, Hardon SF, Lang F, Haney CM, Felinska EA, Kowalewski KF, Müller-Stich BP, Horeman T, Nickel F (2021) Robotic-assisted cholecystectomy is superior to laparoscopic cholecystectomy in the initial training for surgical novices in an ex vivo porcine model: a randomized crossover study. Surg Endosc. https://doi.org/10.1007/s00464-021-08373-6
- Patel HRH, Linares A, Joseph JV (2009) Robotic and laparoscopic surgery: cost and training. Surg Oncol 18:242–246. https://doi. org/10.1016/j.suronc.2009.02.007
- Childers CP, Maggard-Gibbons M (2018) Estimation of the acquisition and operating costs for robotic surgery. JAMA J Am Med Assoc 320:835–836. https://doi.org/10.1001/jama.2018.9219
- Lacitignola L, Trisciuzzi R, Imperante A, Fracassi L, Crovace AM, Staffieri F (2020) Comparison of laparoscopic steerable instruments performed by expert surgeons and novices. Vet Sci. https://doi.org/10.3390/VETSCI7030135
- Siddaiah-Subramanya M, Tiang K, Nyandowe M (2017) A new era of minimally invasive surgery: progress and development of major technical innovations in general surgery over the last decade. Surg J 03:e163–e166. https://doi.org/10.1055/s-0037-16086 51
- Buia A, Stockhausen F, Hanisch E (2015) Laparoscopic surgery: a qualified systematic review. World J Methodol 5:238. https://doi. org/10.5662/wjm.v5.i4.238
- Anderson PL, Lathrop RA, Webster RJ (2016) Robot-like dexterity without computers and motors: a review of hand-held laparoscopic instruments with wrist-like tip articulation. Expert Rev Med Devices 13:661–672. https://doi.org/10.1586/17434440. 2016.1146585
- Romanelli JR, Earle DB (2009) Single-port laparoscopic surgery: an overview. Surg Endosc 23:1419–1427. https://doi.org/10.1007/s00464-009-0463-x
- Sánchez-Margallo JA, Sánchez-Margallo FM (2017) Initial experience using a robotic-driven laparoscopic needle holder with ergonomic handle: assessment of surgeons' task performance and ergonomics. Int J Comput Assist Radiol Surg 12:2069–2077. https://doi.org/10.1007/s11548-017-1636-z
- Supe AN, Kulkarni GV, Supe PA (2010) Ergonomics in laparoscopic surgery. J Minim Access Surg 6:31–36. https://doi.org/10.4103/0972-9941.65161
- Yu D, Lowndes B, Morrow M, Kaufman K, Bingener J, Hallbeck S (2016) Impact of novel shift handle laparoscopic tool on wrist

- ergonomics and task performance. Surg Endosc 30:3480–3490. https://doi.org/10.1007/s00464-015-4634-7
- Corker HP, Singh P, Sodergren MH, Balaji S, Kwasnicki RM, Darzi AW, Paraskeva P (2015) A randomized controlled study to establish the effect of articulating instruments on performance in single-incision laparoscopic surgery. J Surg Educ 72:1–7. https:// doi.org/10.1016/j.jsurg.2014.08.004
- Chow G, Chiu CJ, Zheng B, Panton ON, Meneghetti AT (2016) Rigid vs articulating instrumentation for task completion in single-port surgery. Am J Surg 211:903–907. https://doi.org/10. 1016/j.amjsurg.2016.01.017
- Hardon SF, Schilder F, Bonjer J, Dankelman J, Horeman T (2019) A new modular mechanism that allows full detachability and cleaning of steerable laparoscopic instruments. Surg Endosc 33:3484–3493. https://doi.org/10.1007/s00464-019-06849-0
- 21. Dewaele F, De Pauw T, Kalmar A, Pattyn P, Van Herzeele I, Mottrie A, Van Nieuwenhove Y, Van Roost D (2019) Is the human brain capable of controlling seven degrees of freedom? J Surg Res 238:1–9. https://doi.org/10.1016/j.jss.2019.01.005
- Wee IJY, Kuo LJ, Ngu JCY (2020) A systematic review of the true benefit of robotic surgery: ergonomics. J Med Robot Comput Assist Surg Int. https://doi.org/10.1002/rcs.2113
- Dhariwal A, Prabhu R, Dalvi A, Supe A (2007) Effectiveness of box trainers in laparoscopic training. J Minim Access Surg 3:57–63. https://doi.org/10.4103/0972-9941.33274
- Mohammadi Y, Lerner MA, Sethi AS, Sundaram CP (2010) Comparison of laparoscopy training using the box trainer versus the virtual trainer. J Soc Laparoendosc Surg 14:205–212. https://doi.org/10.4293/108680810X12785289144115
- Willaert W, Van De Putte D, Van Renterghem K, Van Nieuwenhove Y, Ceelen W, Pattyn P (2013) Training models in laparoscopy: a systematic review comparing their effectiveness in learning surgical skills. Acta Chir Belg 113:77–95. https://doi.org/10.1080/00015458.2013.11680892
- Hardon SF, Horeman T, Bonjer HJ, Meijerink WJHJ (2018) Force-based learning curve tracking in fundamental laparoscopic skills training. Surg Endosc 32:3609–3621. https://doi.org/10. 1007/s00464-018-6090-7
- Uysal D, Gasch C, Behnisch R, Nickel F, Müller-Stich BP, Hohenfellner M, Teber D (2020) Evaluation of new motorized articulating laparoscopic instruments by laparoscopic novices using a standardized laparoscopic skills curriculum. Surg Endosc 1:3. https://doi.org/10.1007/s00464-020-08086-2
- Santos BF, Reif TJ, Soper NJ, Hungness ES (2011) Effect of training and instrument type on performance in single-incision laparoscopy: results of a randomized comparison using a surgical simulator. Surg Endosc 25:3798–3804. https://doi.org/10.1007/ s00464-011-1791-1
- Horeman T, Dankelman J, Jansen FW, Van Den Dobbelsteen JJ (2014) Assessment of laparoscopic skills based on force and motion parameters. IEEE Trans Biomed Eng 61:805–813. https:// doi.org/10.1109/TBME.2013.2290052
- Horeman T, Van Delft F, Blikkendaal MD, Dankelman J, Van Den Dobbelsteen JJ, Jansen FW (2014) Learning from visual force feedback in box trainers: tissue manipulation in laparoscopic surgery. Surg Endosc. https://doi.org/10.1007/s00464-014-3425-x
- 31. Smit D, Spruit E, Dankelman J, Tuijthof G, Hamming J, Horeman T (2017) Improving training of laparoscopic tissue manipulation skills using various visual force feedback types. Surg Endosc 31:299–308. https://doi.org/10.1007/s00464-016-4972-0

**Publisher's Note** Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

